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1 ' GestionParking3.B4R
2 #Region Project Attributes
3     #AutoFlushLogs: True
4     #CheckArrayBounds: True
5     #StackBufferSize: 300
6 #End Region
7
8 ' GESTION D'UN PARKING VIRTUEL DE 10 PLACES VIDE AU DÉPART >>> 10 places sont libres >>>
9 ' 10 LEDs vertes sont allumées
10 ' Marc DANIEL - via CARTE ARDUINO UNO complétée par l'utilisation du composant L293D -
11 ' Mars 2021
12 ' Maquette de Parking avec moteur + réducteur et ouverture directe de la barrière
13
14 Sub Process_Globals
15     Public Serial1 As Serial
16     Private pinButtonEntree As Pin 'broche pour le bouton d'entrée du parking
17     Private pinButtonSortie As Pin 'broche pour le bouton de sortie du parking
18     Private pinBuzzer As Pin 'broche pour le buzzer
19     Private pinLED1, pinLED2, pinLED3, pinLED4, pinLED5, pinLED6, pinLED7, pinLED8,
20     pinLED9, pinLED10, pinLEDrouge As Pin 'broches pour les LEDs
21     Public LED1 = False As Boolean
22     Public LED2 = False As Boolean
23     Public LED3 = False As Boolean
24     Public LED4 = False As Boolean
25     Public LED5 = False As Boolean
26     Public LED6 = False As Boolean
27     Public LED7 = False As Boolean
28     Public LED8 = False As Boolean
29     Public LED9 = False As Boolean
30     Public LED10 = False As Boolean
31     Public LEDrouge = False As Boolean
32     Private pinOuverture, pinFermeture As Pin 'broches de sorties pour les connexions
33     motorisation barrière
34     Public Places As UInt
35 End Sub
36
37 Private Sub AppStart
38     Serial1.Initialize(115200)
39     pinButtonEntree.Initialize(pinButtonEntree.A0, pinButtonEntree.MODE_INPUT_PULLUP)
40     pinButtonEntree.AddListener("pinButtonEntree_StateChanged")
41     pinButtonSortie.Initialize(pinButtonSortie.A1, pinButtonSortie.MODE_INPUT_PULLUP)
42     pinButtonSortie.AddListener("pinButtonSortie_StateChanged")
43     pinLED1.Initialize(10, pinLED10.MODE_OUTPUT)
44     pinLED2.Initialize(2, pinLED2.MODE_OUTPUT)
45     pinLED3.Initialize(3, pinLED3.MODE_OUTPUT)
46     pinLED4.Initialize(4, pinLED4.MODE_OUTPUT)
47     pinLED5.Initialize(5, pinLED5.MODE_OUTPUT)
48     pinLED6.Initialize(6, pinLED6.MODE_OUTPUT)
49     pinLED7.Initialize(7, pinLED7.MODE_OUTPUT)
50     pinLED8.Initialize(8, pinLED8.MODE_OUTPUT)
51     pinLED9.Initialize(9, pinLED9.MODE_OUTPUT)
52     pinLED10.Initialize(11, pinLED10.MODE_OUTPUT)
53     pinLEDrouge.Initialize(19, pinLEDrouge.MODE_OUTPUT) 'Broche analogique A5
54     pinBuzzer.Initialize(18, pinBuzzer.MODE_OUTPUT) 'Broche analogique A4
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52   pinOuverture.Initialize(12, pinOuverture.MODE_OUTPUT) 'Connexion au composant L293D  ↗
    borne "IN2" pour l'ouverture de la barrière
53   pinFermeture.Initialize (13, pinFermeture.MODE_OUTPUT) 'Connexion au composant L293D  ↗
    borne "IN1" pour la fermeture de la barrière (et allumage de la diode 13 Arduino)
54   Places=10 '10 places de parking sont libres au démarrage - Le parking est vide
55   CallSubPlus("Depart", 0,0)
56
57 End Sub
58
59 Private Sub Depart ' Ily a 10 places de libres - les 10 LEDs vertes sont allumées au  ↗
    départ
60   pinLED1.DigitalWrite(True)
61   pinLED2.DigitalWrite(True)
62   pinLED3.DigitalWrite(True)
63   pinLED4.DigitalWrite(True)
64   pinLED5.DigitalWrite(True)
65   pinLED6.DigitalWrite(True)
66   pinLED7.DigitalWrite(True)
67   pinLED8.DigitalWrite(True)
68   pinLED9.DigitalWrite(True)
69   pinLED10.DigitalWrite(True)
70 End Sub
71
72 Private Sub pinButtonEntree_StateChanged(State1 As Boolean)
73   Log("État: ", State1) 'Log la valeur de State1
74   If State1 = False Then
75       If Places = 0 Then CallSubPlus("GestionPlaces", 0, 0)
76           If Places > 0 Then
77               Places = Places -1
78               CallSubPlus("Buzzer",0,0)
79               CallSubPlus("GestionPlaces",0,0)
80               CallSubPlus("Ouverture",500,0) ' Ouverture de la barrière
81               CallSubPlus("Pause",5150,0) 'Mouvement du véhicule
82               CallSubPlus("Fermeture", 10300, 0) ' Fermeture de la barrière
83               CallSubPlus("FinEntree",15000,0) ' Fin de la fermeture de la barrière
84           End If
85       End If
86 End Sub
87
88 Private Sub pinButtonSortie_StateChanged(State2 As Boolean)
89   Log("État: ", State2) 'Log la valeur de State2
90   If State2 = False Then
91       If Places = 10 Then CallSubPlus("GestionPlaces",0, 0)
92       If Places < 10 Then
93           Places=Places + 1
94           CallSubPlus("GestionPlaces",0,0)
95           CallSubPlus("Ouverture",200,0) ' Ouverture de la barrière
96           CallSubPlus("Pause",4850,0) 'Mouvement du véhicule
97           CallSubPlus("Fermeture", 10000, 0) ' Fermeture de la barrière
98           CallSubPlus("FinSortie",14700,0) ' Fin de la fermeture de la barrière
99       End If
100      End If
101 End Sub
102
103 Private Sub Ouverture(Tag As Byte)
104   pinBuzzer.DigitalWrite(False)
105   pinOuverture.DigitalWrite(True) ' ouvre la barrière pour entrée ou sortie d'un  ↗
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véhicule
106 End Sub
107
108 Private Sub Pause(Tag As Byte)
109     pinOuverture.DigitalWrite(False) 'La barrière reste ouverte - Mouvement du véhicule ↗
110     entrant ou sortant
111 End Sub
112
112 Private Sub Fermeture(Tag As Byte)
113     pinFermeture.DigitalWrite(True) 'fermeture de la barrière
114 End Sub
115
116 Private Sub FinEntree(Tag As Byte)
117     pinFermeture.DigitalWrite(False) 'Arrêt de la fermeture de la barrière
118
119 End Sub
120
121 Private Sub FinSortie(Tag As Byte)
122     pinFermeture.DigitalWrite(False) 'Arrêt de la fermeture de la barrière
123 End Sub
124
125 Private Sub Buzzer(Tag As Byte)
126     pinBuzzer.DigitalWrite(True)
127 End Sub
128
129
130 Private Sub GestionPlaces
131     Select Places
132     Case 0
133         pinLED1.DigitalWrite(False)
134         pinLED2.DigitalWrite(False)
135         pinLED3.DigitalWrite(False)
136         pinLED4.DigitalWrite(False)
137         pinLED5.DigitalWrite(False)
138         pinLED6.DigitalWrite(False)
139         pinLED7.DigitalWrite(False)
140         pinLED8.DigitalWrite(False)
141         pinLED9.DigitalWrite(False)
142         pinLED10.DigitalWrite(False)
143         pinLEDrouge.DigitalWrite(True) 'allume la LED rouge (plus de places)
144     Case 1
145         pinLEDrouge.DigitalWrite(False) 'éteint la LED Rouge
146         pinLED1.DigitalWrite(True) ' Une place est libre
147         pinLED2.DigitalWrite(False)
148         pinLED3.DigitalWrite(False)
149         pinLED4.DigitalWrite(False)
150         pinLED5.DigitalWrite(False)
151         pinLED6.DigitalWrite(False)
152         pinLED7.DigitalWrite(False)
153         pinLED8.DigitalWrite(False)
154         pinLED9.DigitalWrite(False)
155         pinLED10.DigitalWrite(False)
156     Case 2
157         pinLED1.DigitalWrite(True)
158         pinLED2.DigitalWrite(True)
159         pinLED3.DigitalWrite(False)
160         pinLED4.DigitalWrite(False)
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161     pinLED5.DigitalWrite(False)
162     pinLED6.DigitalWrite(False)
163     pinLED7.DigitalWrite(False)
164     pinLED8.DigitalWrite(False)
165     pinLED9.DigitalWrite(False)
166     pinLED10.DigitalWrite(False)
167     Case 3
168     pinLED1.DigitalWrite(True)
169     pinLED2.DigitalWrite(True)
170     pinLED3.DigitalWrite(True)
171     pinLED4.DigitalWrite(False)
172     pinLED5.DigitalWrite(False)
173     pinLED6.DigitalWrite(False)
174     pinLED7.DigitalWrite(False)
175     pinLED8.DigitalWrite(False)
176     pinLED9.DigitalWrite(False)
177     pinLED10.DigitalWrite(False)
178     Case 4
179     pinLED1.DigitalWrite(True)
180     pinLED2.DigitalWrite(True)
181     pinLED3.DigitalWrite(True)
182     pinLED4.DigitalWrite(True)
183     pinLED5.DigitalWrite(False)
184     pinLED6.DigitalWrite(False)
185     pinLED7.DigitalWrite(False)
186     pinLED8.DigitalWrite(False)
187     pinLED9.DigitalWrite(False)
188     pinLED10.DigitalWrite(False)
189     Case 5
190     pinLED1.DigitalWrite(True)
191     pinLED2.DigitalWrite(True)
192     pinLED3.DigitalWrite(True)
193     pinLED4.DigitalWrite(True)
194     pinLED5.DigitalWrite(True)
195     pinLED6.DigitalWrite(False)
196     pinLED7.DigitalWrite(False)
197     pinLED8.DigitalWrite(False)
198     pinLED9.DigitalWrite(False)
199     pinLED10.DigitalWrite(False)
200     Case 6
201     pinLED1.DigitalWrite(True)
202     pinLED2.DigitalWrite(True)
203     pinLED3.DigitalWrite(True)
204     pinLED4.DigitalWrite(True)
205     pinLED5.DigitalWrite(True)
206     pinLED6.DigitalWrite(True)
207     pinLED7.DigitalWrite(False)
208     pinLED8.DigitalWrite(False)
209     pinLED9.DigitalWrite(False)
210     pinLED10.DigitalWrite(False)
211     Case 7
212     pinLED1.DigitalWrite(True)
213     pinLED2.DigitalWrite(True)
214     pinLED3.DigitalWrite(True)
215     pinLED4.DigitalWrite(True)
216     pinLED5.DigitalWrite(True)
217     pinLED6.DigitalWrite(True)
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218         pinLED7.DigitalWrite(True)
219         pinLED8.DigitalWrite(False)
220         pinLED9.DigitalWrite(False)
221         pinLED10.DigitalWrite(False)
222     Case 8
223         pinLED1.DigitalWrite(True)
224         pinLED2.DigitalWrite(True)
225         pinLED3.DigitalWrite(True)
226         pinLED4.DigitalWrite(True)
227         pinLED5.DigitalWrite(True)
228         pinLED6.DigitalWrite(True)
229         pinLED7.DigitalWrite(True)
230         pinLED8.DigitalWrite(True)
231         pinLED9.DigitalWrite(False)
232         pinLED10.DigitalWrite(False)
233     Case 9
234         pinLED1.DigitalWrite(True)
235         pinLED2.DigitalWrite(True)
236         pinLED3.DigitalWrite(True)
237         pinLED4.DigitalWrite(True)
238         pinLED5.DigitalWrite(True)
239         pinLED6.DigitalWrite(True)
240         pinLED7.DigitalWrite(True)
241         pinLED8.DigitalWrite(True)
242         pinLED9.DigitalWrite(True)
243         pinLED10.DigitalWrite(False)
244     Case 10
245         pinLED1.DigitalWrite(True)
246         pinLED2.DigitalWrite(True)
247         pinLED3.DigitalWrite(True)
248         pinLED4.DigitalWrite(True)
249         pinLED5.DigitalWrite(True)
250         pinLED6.DigitalWrite(True)
251         pinLED7.DigitalWrite(True)
252         pinLED8.DigitalWrite(True)
253         pinLED9.DigitalWrite(True)
254         pinLED10.DigitalWrite(True)
255     End Select
256 End Sub
257
258
259
260
```